



## R-ROSS Robbdos Remotely Operated Survey System

December 2024

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# DE DONDE VENGO! - ETSIN UPM – CEHINAV



POLITÉCNICA



## RobdoS Team



Robdos Team promueve la robótica de campo en el ámbito académico de la UPM, agrupando a estudiantes de distintas ingenierías que desarrollan SW y HW para un robot submarino



# ROBDOS SRL – Inicios (2013)

Nuestra Start-Up se dedica a desarrollos de plataformas robóticas y sistemas de automatización y monitorización en el medio marino

## FUNDADORES



### HUGO RAMOS

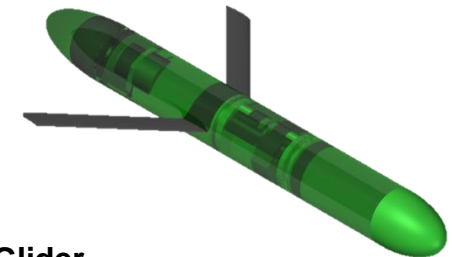
Ingeniero Naval y Oceánico  
Gestión de Proyectos tecnológicos  
Diseño de sistemas embarcados



### PIERRE SOULARD

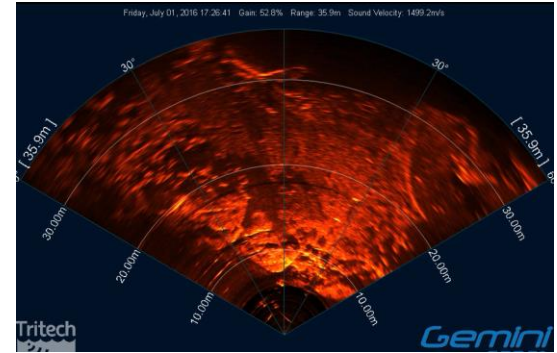
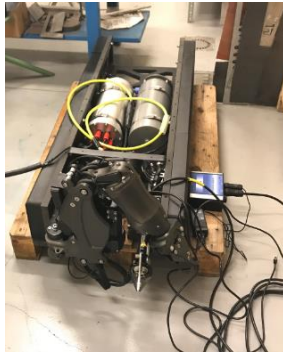
MBA  
Consultant in the banking sector  
Strong international experience

## NUESTRA SEDE

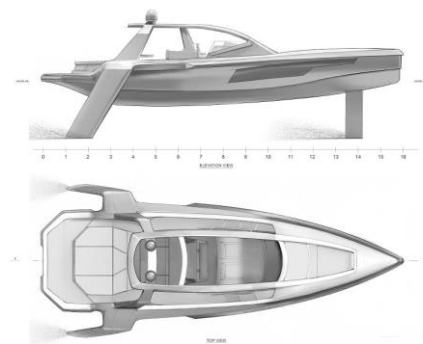
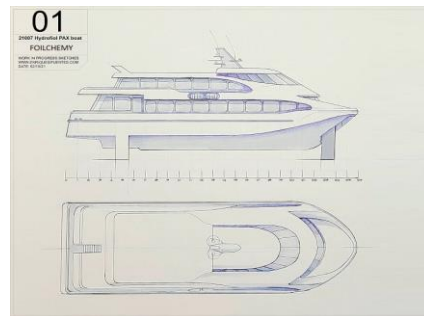


**Glider**  
Submarine Robot  
Glider

## H-AUV Hybrid Autonomous Underwater Vehicle



**FOILCHEMY**



**Naia – First of a kind!**  
Sailing dinghy on hydrofoil,  
electronically controlled by an  
on-board system

# ACTUALIDAD- HRC ENGINEERING SL

OPERACIONES MARINAS



SERVICIOS DE CONSULTORÍA

PROYECTOS DE ARQUITECTURA NAVAL



# ROBDOS OVERVIEW – QUE NOS GUSTARÍA HACER !



## AUTONOMOUS PLATFORMS

Hybrid platforms

Benthic landers and smart buoys

Modular Payload

## CLOUD BASED SW PLATFORM

Ground stations

Flexible and modular SW

Data security & management

## VALUE INNOVATION

Commercial exploitation model benefiting from transversal HW and SW developments and third-party systems integration

COST

Value Innovation

BUYER VALUE



# QUE SOMOS CAPACES DE HACER? Systems examples

## Resident on infrastructure systems



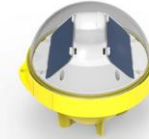
Submarino esperando a desconectar



Systems able to perform 24/7 inspections around a critical asset in the underwater infrastructure. Like the earlier develop by our tech staff and shown in the above pictures.

This system prototype is able inspect an underwater pipe from shore to mono buoy near the refinery and to be recharged at an underwater docking station/garage.

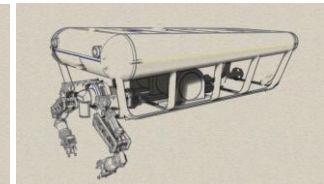
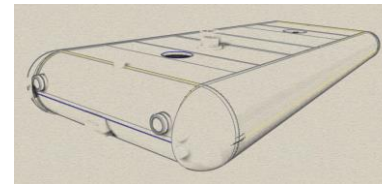
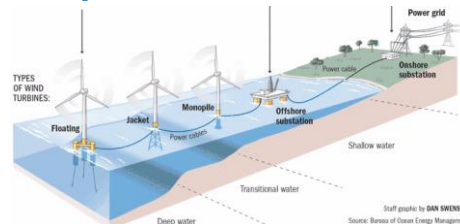
## Benthic landers and smart buoys



Smart connected buoys, equipped with an specific payload able to provide strategic data to the operator through our SW platform.

The same purpose will be covered on the seafloor by benthic landers (underwater system stations) at specific points of interest on the seabed.

## Hybrid platforms, tailored developments



This advanced vehicle concept, coupled with our SW platforms is able to be adapted from the low energy consumption and efficient navigation scenarios of an AUV to the ROV operations where mechanical actuation tools and an umbilical cables are implemented on a lower structural frame in order to allow the system to perform this energy demanding tasks.

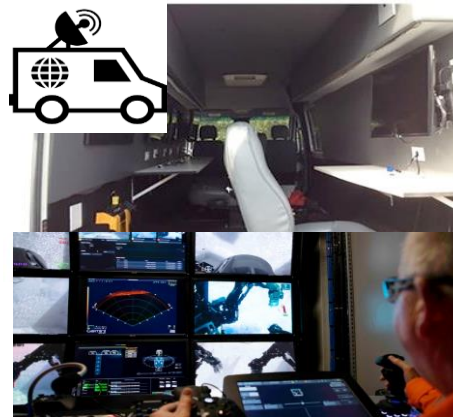
# R-ROSS – POR DONDE HEMOS EMPEZADO!

R-ROSS Robdos Remotely Operated Surey System , a robotic marine survey system capable of operate in near shore scenarios with a great flexibility of different robots (surface, underwater and aerial), payload and the capacity of real time transmission of the survey information to the client central offices

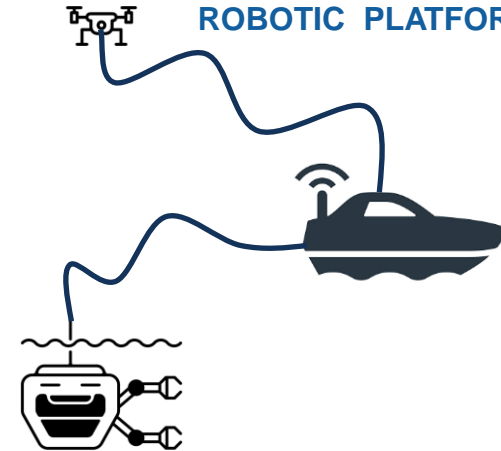
## CLIENT CENTRAL OFFICES



## SHORE MONITORING & CONTROL STATION



## REMOTELY OPERATED ROBOTIC PLATFORMS



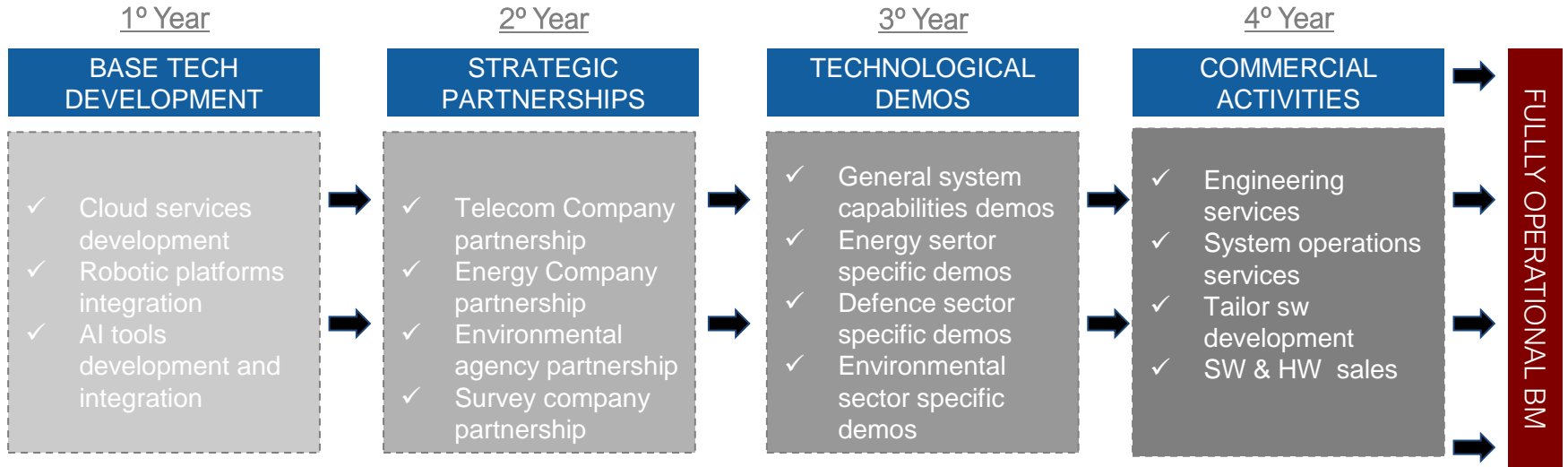
This innovative system, supported by Robdos Service Web Platform presents several advantages when compared with tradition survey methods:

- Cheaper and more flexible operations
- Real time remote monitoring (direct connection to the client central offices )
- Reduction of the risk of the human life at sea
- Greater operational window
- Higher inspection speed while being able to go deeper that divers



# COMO LO HAREMOS?

Following and open innovation and agile model of technological development where our clients and their operational need stand in the center of our business model



# Equipo de Colaboradores



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Robotics & Technical Director | Driving Technological and Operational Efficiency in Supply Chain

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Project Manager; Offshore Technology

Greater Madrid Metropolitan Area · [Contact info](#)



**Servando Germán Serrano** · 1st

Robotics Engineering Lead at Unipart Digital

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326 connections



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Robotics Engineering

Oviedo, Principality of Asturias, Spain · [Contact info](#)

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